

The GPS Data Campaign for the Slip Surface Estimation Ciloto Landslide Zone, West Java, Indonesia

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Ciloto zone consist of breccia rock, clay soil, silt soil



Debris material

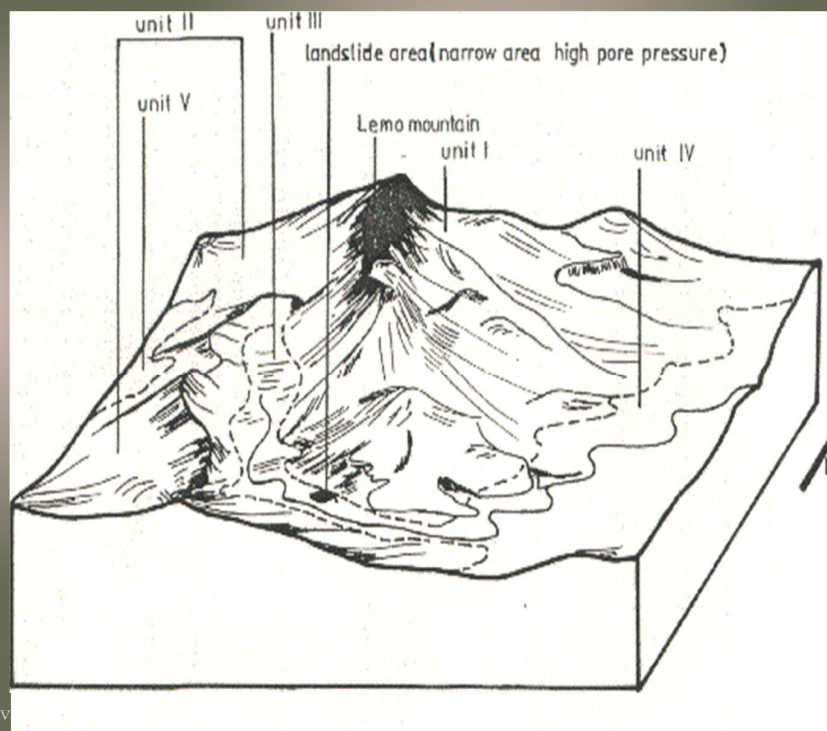
Mass Movement Indication in Ciloto Zone



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Morphology at Ciloto Area

- Unit I : Gunung Lemo Area
 - Unit II : Pondok Cikoneng Area, Gunung Mas, Gunung Gedogan, and Gunung Joglok
 - Unit III : Puncak, Jember Area
 - Unit IV : Sindanglaya Area
 - Unit V : Cempaka Slope Area, Tugu
- (Sugalang, 1989)



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Methodology – Geometric Method

Static model :

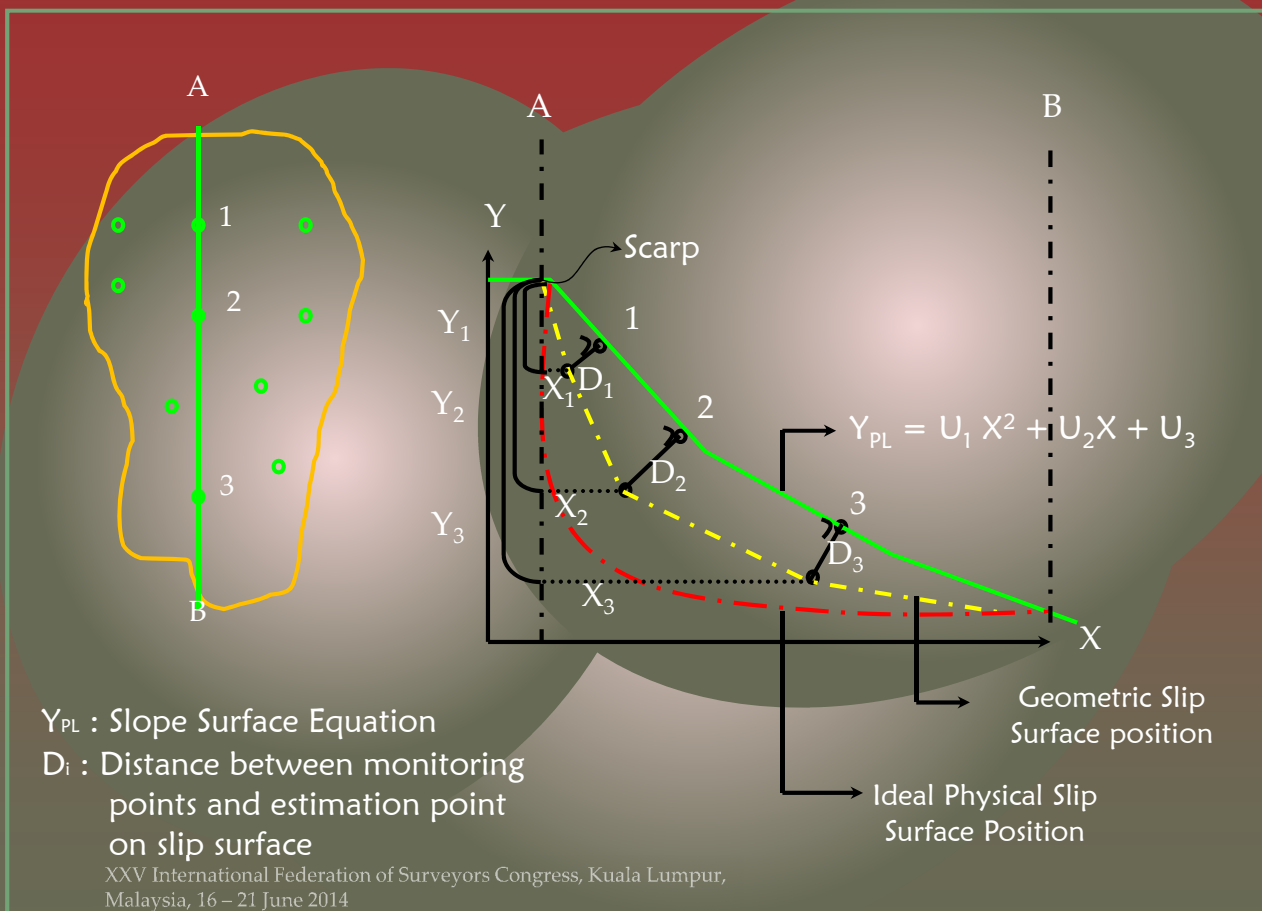
& Status vector of horizontal and vertical displacement

Kinematic model :

& Status vector of horizontal and vertical displacement

& Velocity and acceleration of material displacement

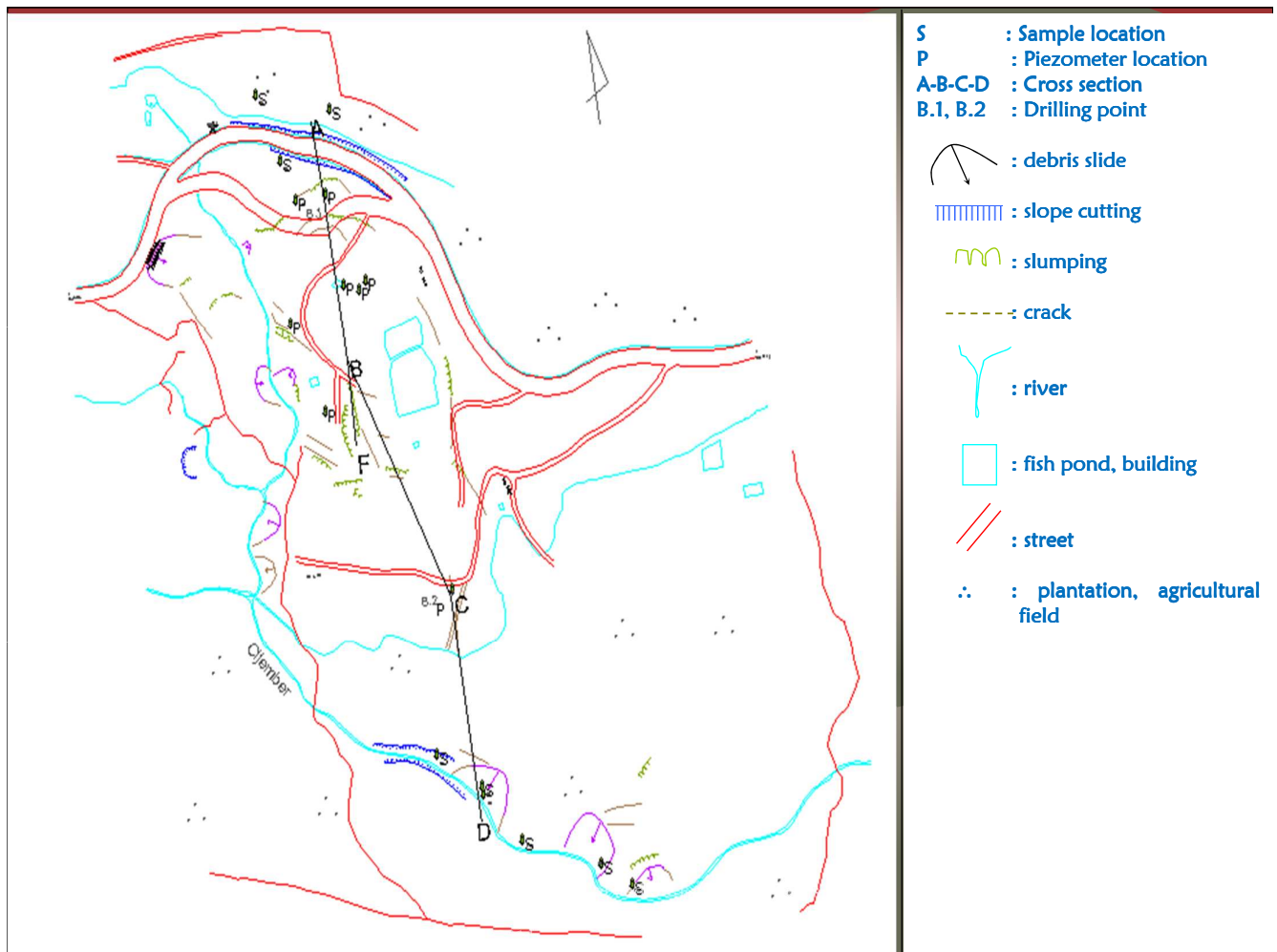
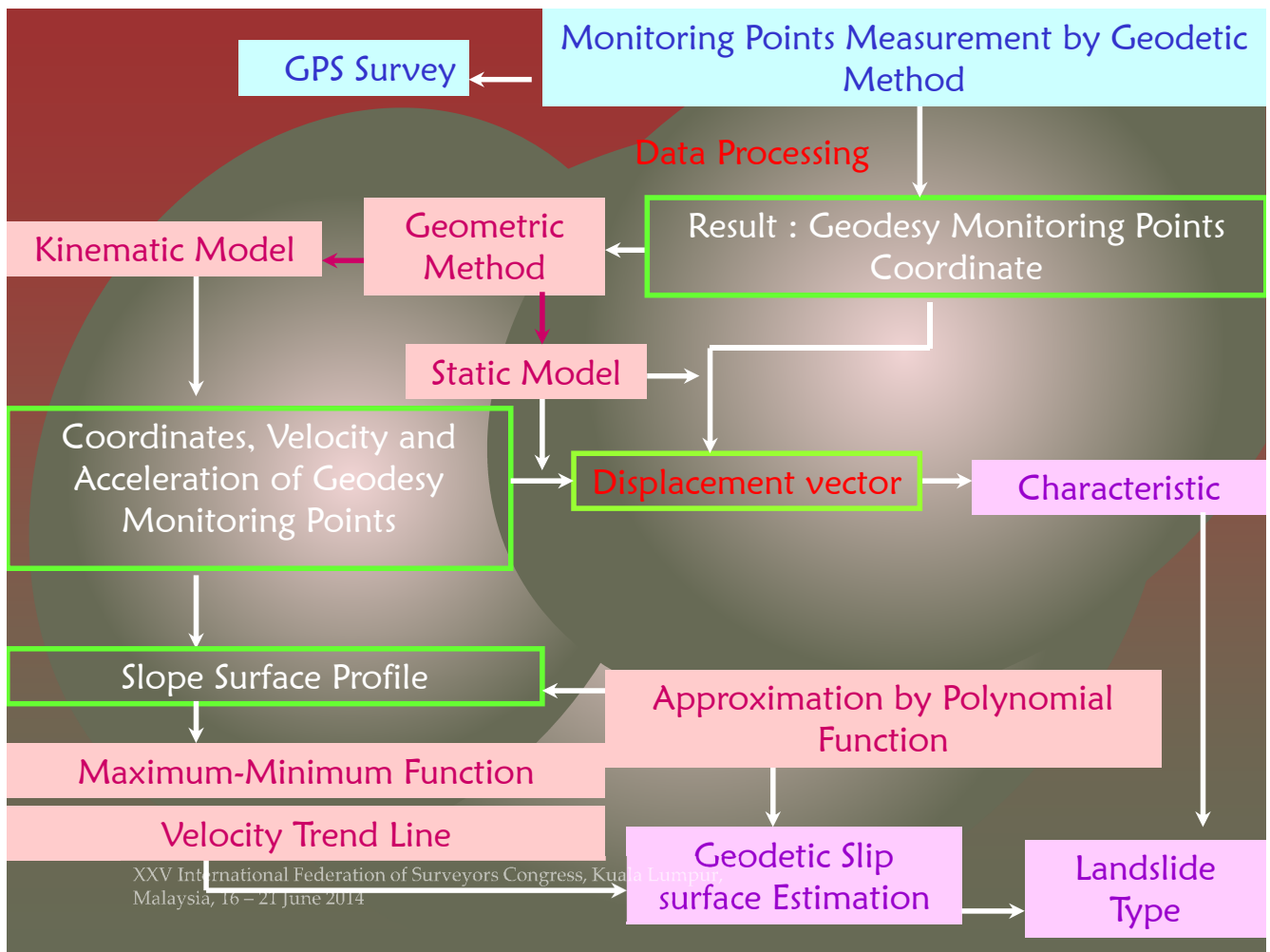
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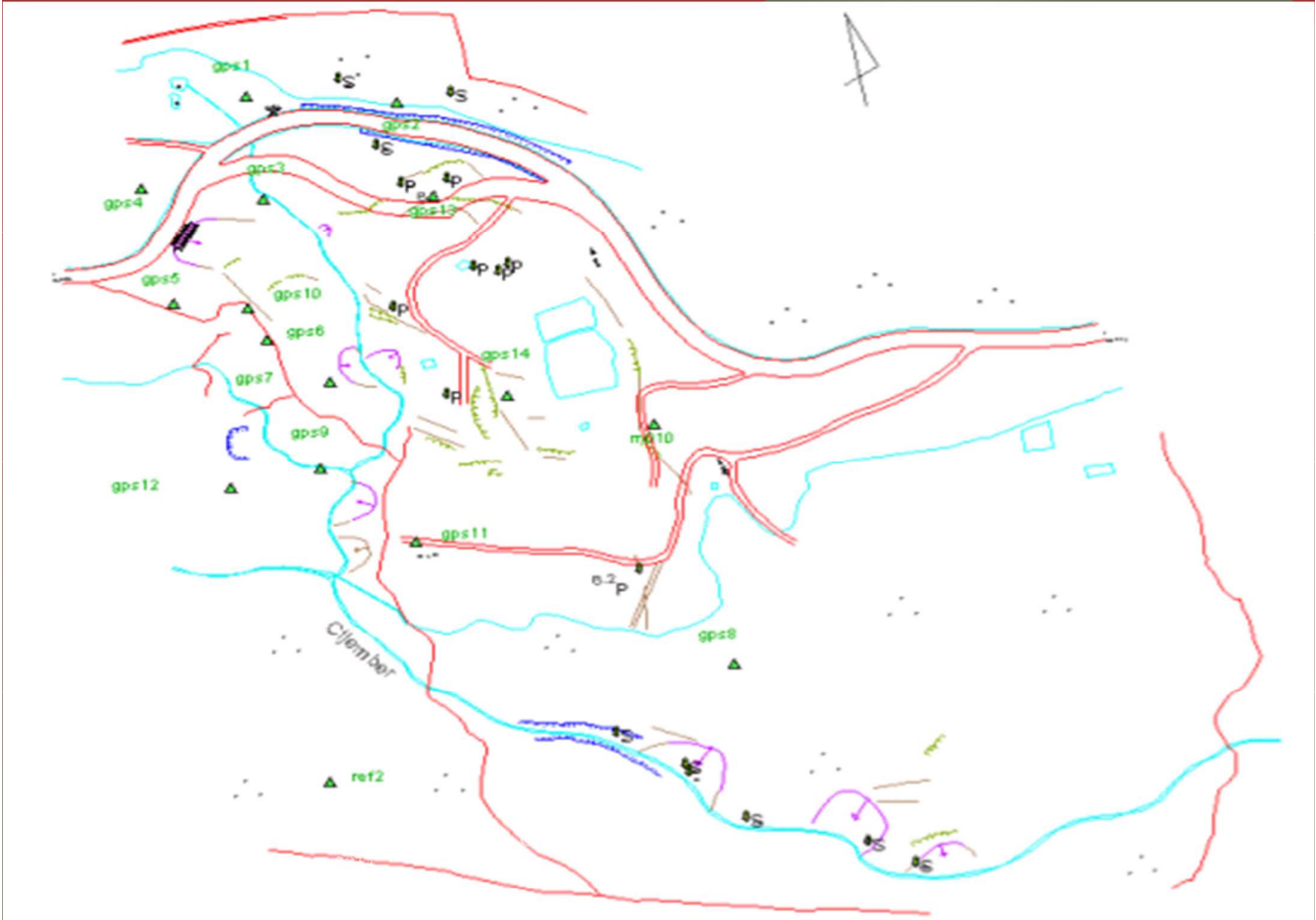
Y_{PL} : Slope Surface Equation

D_i : Distance between monitoring points and estimation point on slip surface

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GPS SURVEY (2002-2005)



GPS Survey Strategy

Measurement Method	Differential Static
Equipment Type	Dual Frequency , Geodetic type
Data Type	P and C/A code Carrier phase
Duration	4 - 6 hour
Epoch Interval	30 "
Elevation Mask	15 °

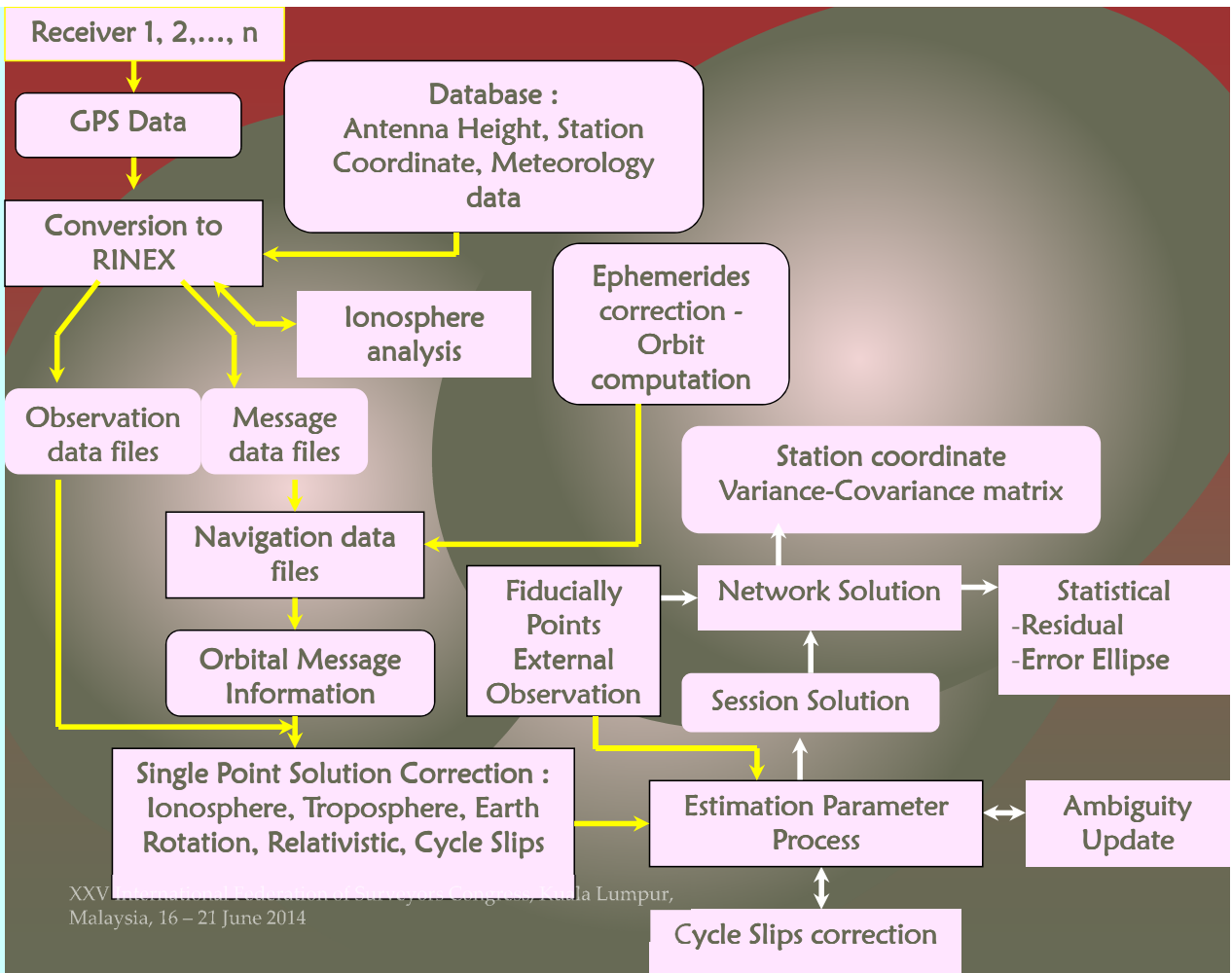
GPS Measurement Campaign

- Epoch 1 : 21-22 January 2002
- Epoch 2 : 04-05 April 2002
- Epoch 3 : 10 Mei 2003
- Epoch 4 : 14-15 Mei 2004
- Epoch 5 : 03-04 July 2005

GPS Receiver type

Receiver	Unit
Ashtech Z-XII3	3
Trimble 4000SSi	7
Leica SR9500	2
Leica SR520	2

GPS Data Processing



Kinematic Model

Equations (Yalcinkaya dan Bayrak, 2004) :

$$E_j^{(i)} = E_j^{(i-1)} + (t_i - t_{i-1})V_{Ej} + \frac{1}{2}(t_i - t_{i-1})^2 a_{Ej}$$

$$N_j^{(i)} = N_j^{(i-1)} + (t_i - t_{i-1})V_{Nj} + \frac{1}{2}(t_i - t_{i-1})^2 a_{Nj}$$

$$h_j^{(i)} = h_j^{(i-1)} + (t_i - t_{i-1})V_{hj} + \frac{1}{2}(t_i - t_{i-1})^2 a_{hj}$$

Calculation of vector status prediction (scalar, velocity and acceleration) by Kalman Filtering Method

Kalman Filtering

$$\bar{Y}_{i,1} = \begin{bmatrix} E \\ N \\ h \\ V_E \\ V_N \\ V_h \\ a_E \\ a_N \\ a_h \end{bmatrix}_{i,1} = \begin{bmatrix} I_{3,3} & I_{3,3}(t_i - t_{i-1}) & I_{3,3} \frac{(t_i - t_{i-1})^2}{2} \\ 0_{3,3} & I_{3,3} & I_{3,3}(t_i - t_{i-1}) \\ 0_{3,3} & 0_{3,3} & I_{3,3} \end{bmatrix} \begin{bmatrix} E \\ N \\ h \\ V_E \\ V_N \\ V_h \\ a_E \\ a_N \\ a_h \end{bmatrix}_{(i-1),1}$$

$$Q_{Y_i, Y_i} = T_{i, (i-1)} Q_{Y(i-1), Y(i-1)} T_{i, (i-1)}^T$$

$$\hat{L}_{i,1} = L_{i,1} + v_{Li,1} = A_{i,i} \hat{Y}_{i,1}$$

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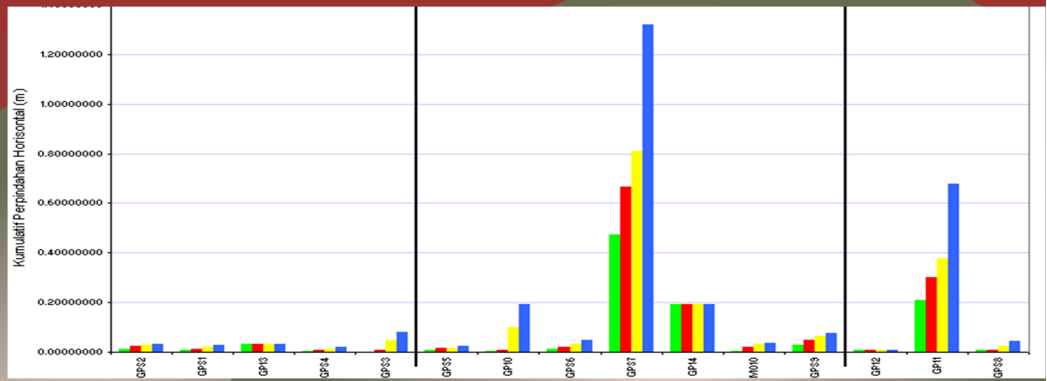
Result-1

⊗ Status vector of horizontal and vertical displacement

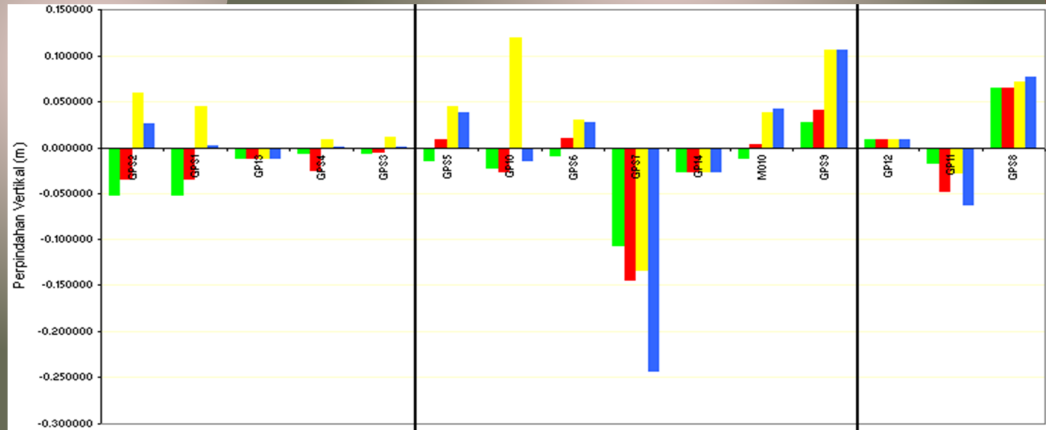
- ⊗ Quantification of material displacement
- ⊗ Comparison of displacement characteristic of landslide zone common with single sliding → **head, depletion zone (in middle), accumulation zone (foot-toe) to find movement mechanism**
→ **single/successive/multiple/retrogressive sliding**
- ⊗ Comparison between horizontal and vertical (negative-positive) displacement of monitored point → **terrain profile to find minor scarp position, subsidence & bulging** → **translational/rotational slide**

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Kinematic M. : Cumulative Horizontal Displacement



Kinematic M. : Cumulative Vertical Displacement



- █ Epoch 1-2
- █ Epoch 2-3
- █ Epoch 3-4
- █ Epoch 4-5

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Top of Landslide
zone

Middle of Landslide
zone

Toe of
Landslide zone

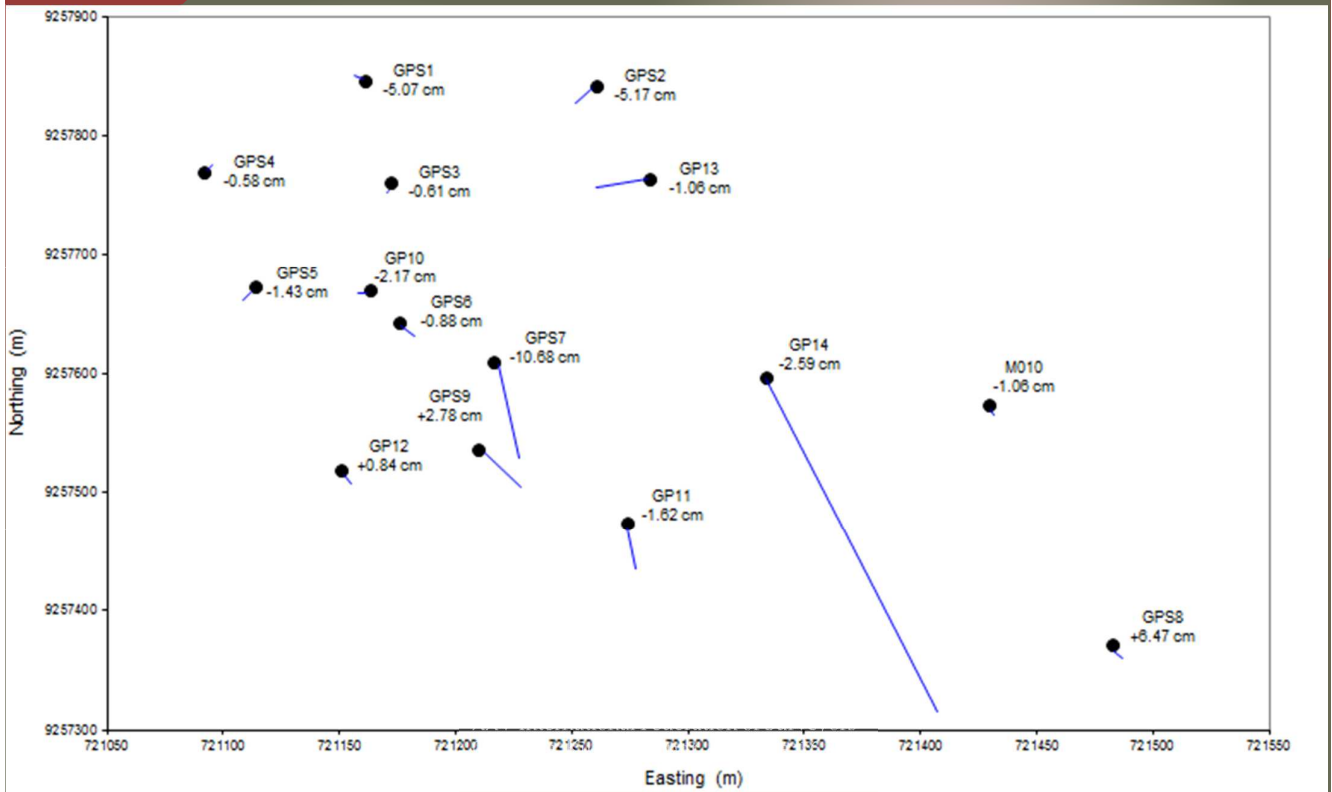
Result-2

Kinematic Model

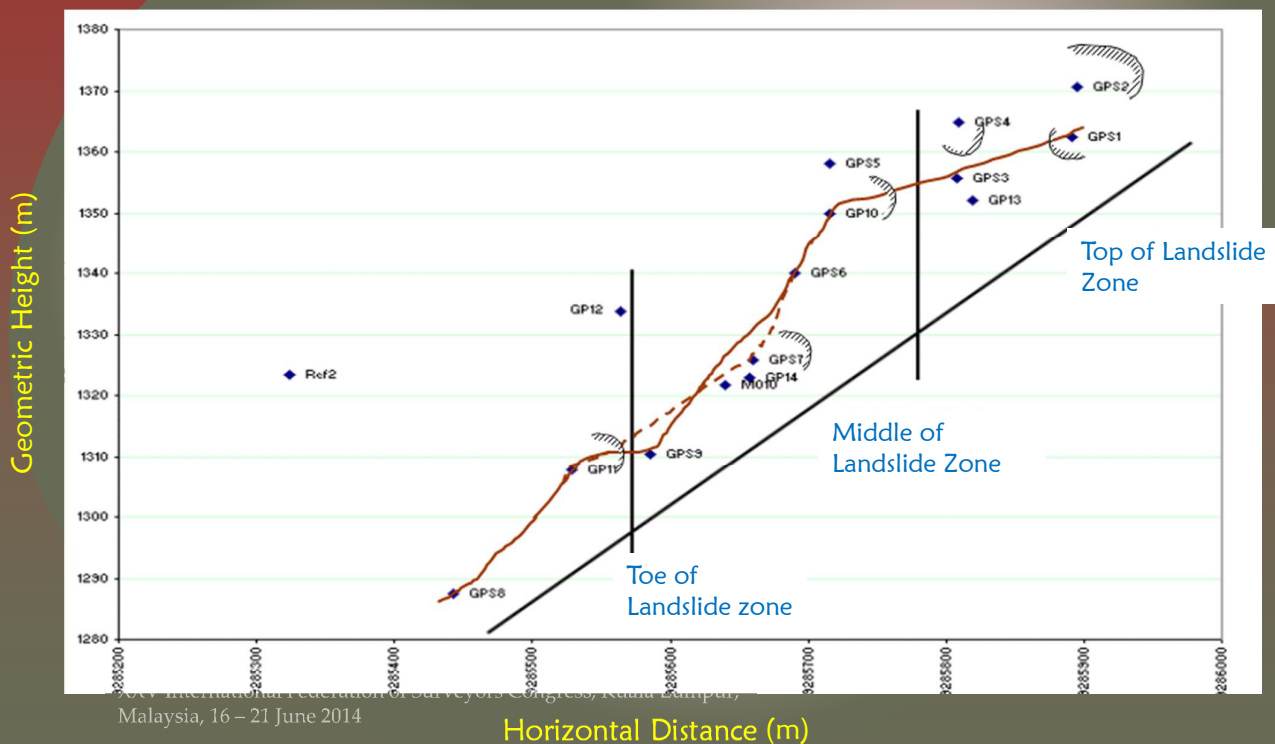
- ⊗ Velocity and acceleration of material displacement
 - ⊗ High horizontal velocity in depletion zone
 - ⊗ High vertical velocity in head (vertical -) and accumulation zone (positive +)

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Illustration of Horizontal Displacement

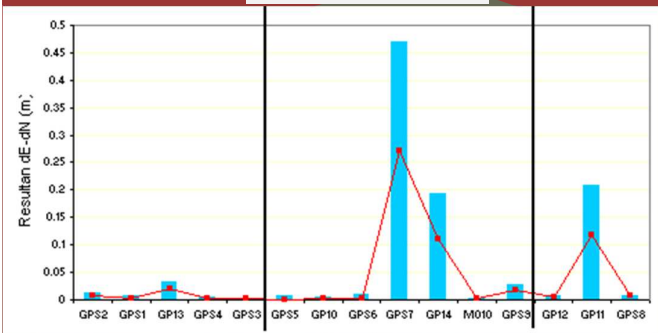


Vertical profile

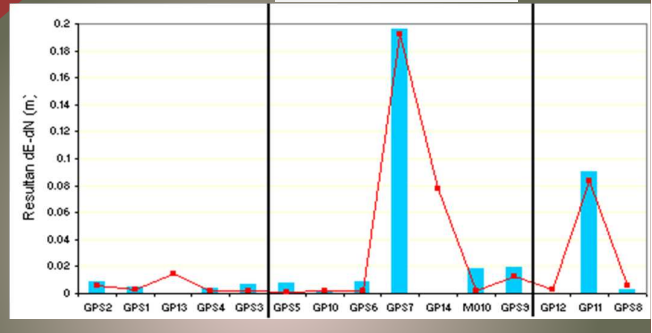


Velocity – Displacement (Horizontal)

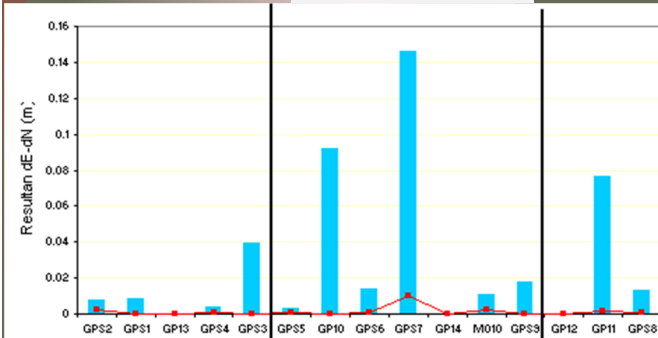
Epoch 1-2



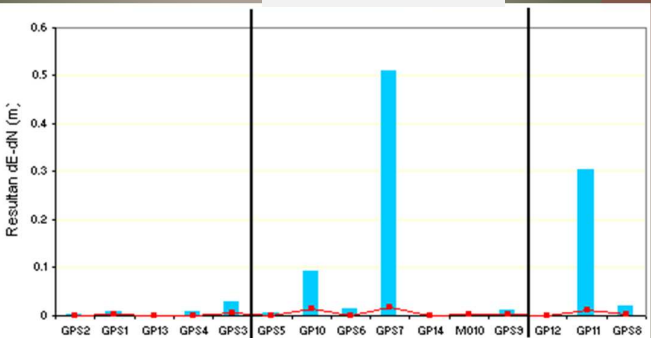
Epoch 2-3



Epoch 3-4



Epoch 4-5



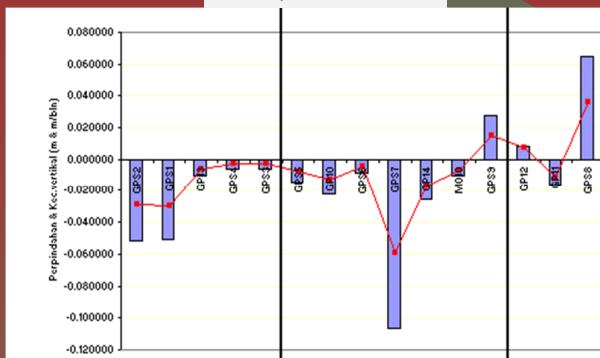
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Horizontal Displacement

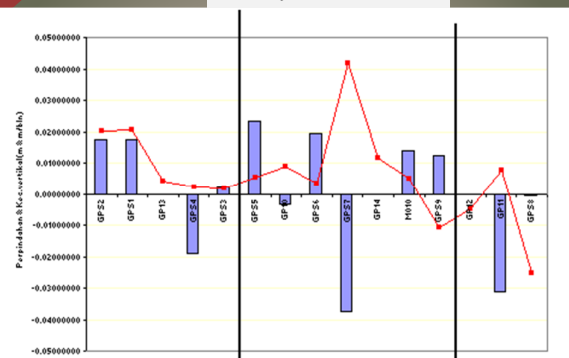
Horizontal Velocity

Velocity – Displacement (Vertical)

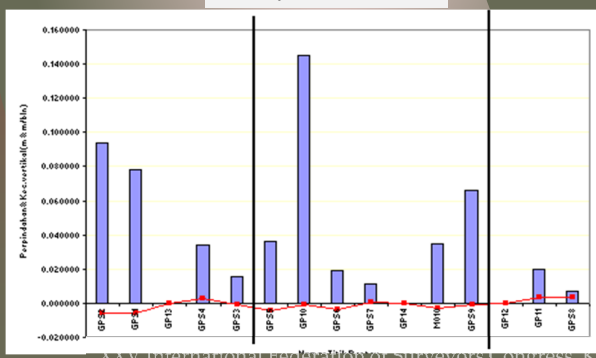
Epoch 1-2



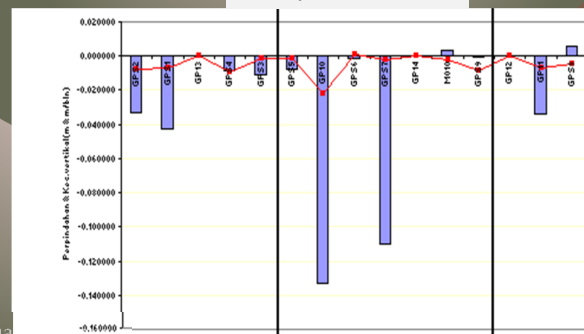
Epoch 2-3



Epoch 3-4



Epoch 4-5

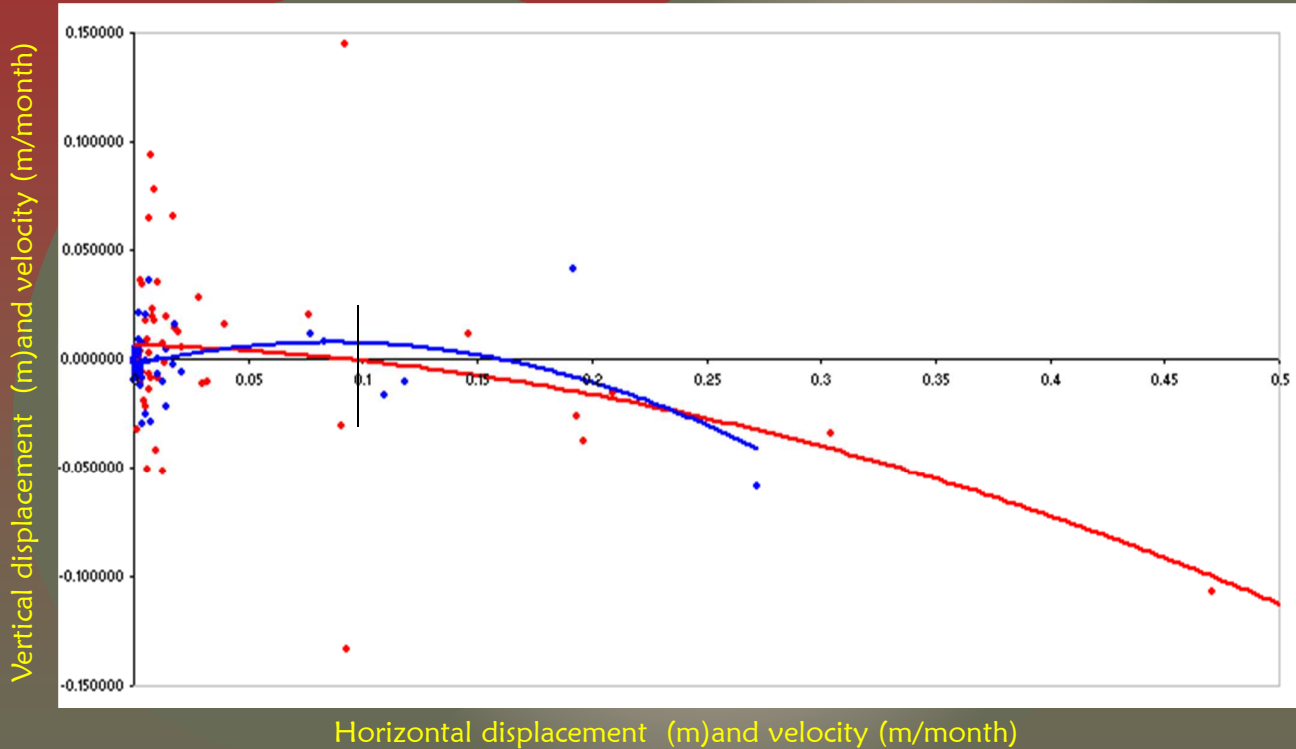


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Vertical Displacement

Vertical Velocity

Relation of Displacement and Velocity



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— Displacement (Polynomial) — Velocity (Polynomial)

Discussion

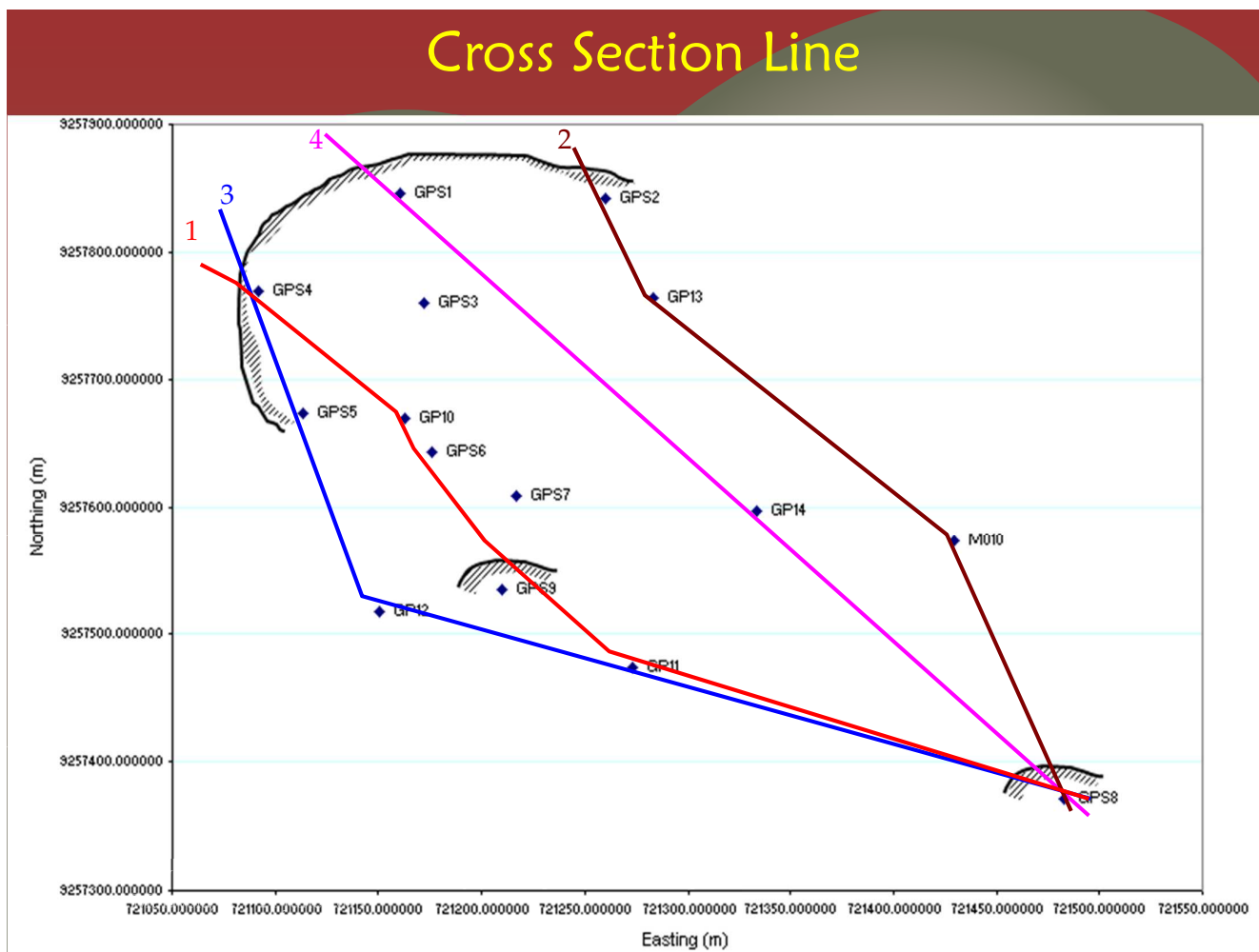
⌘ Vector Status of Position and Velocity

- ⌘ Evacuation area
- ⌘ Position of instability point (subsidence and bulging)
- ⌘ Position of stability point (breakline)

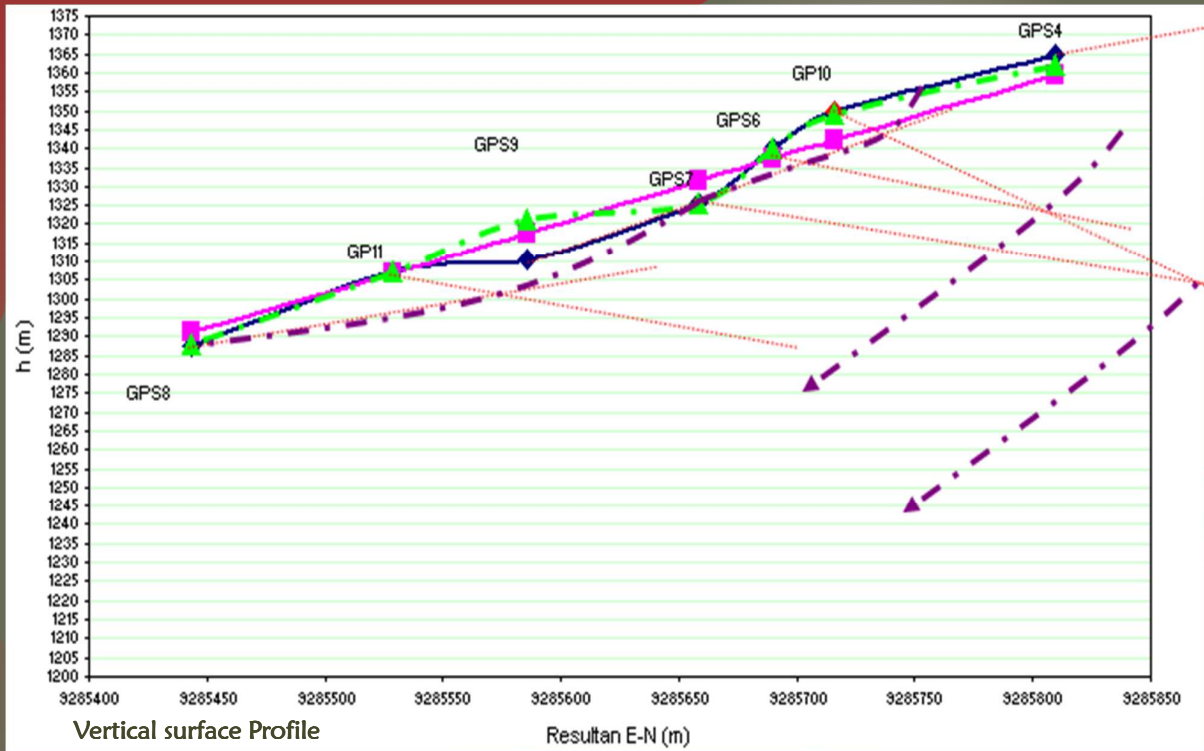
⌘ New Minor Scarp

- ⌘ Retrogressive indication
- ⌘ New scarp caused new external factor

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Cross Section Line 1st



Approx. Surface from
Kinematic model

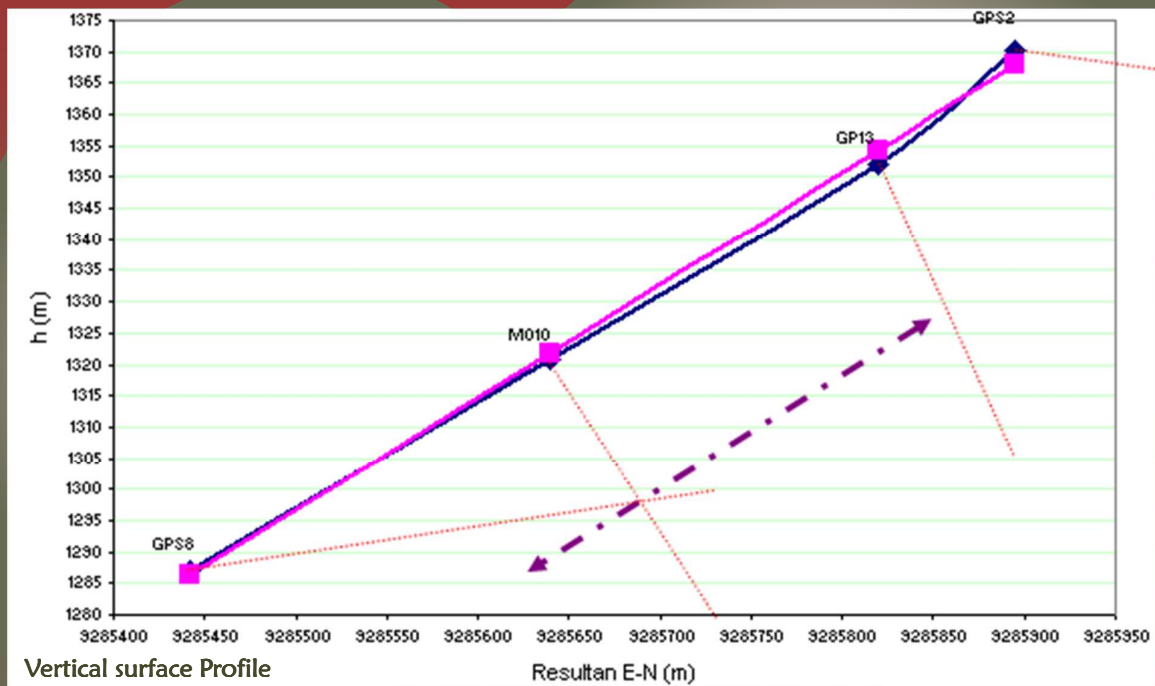
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Approx. Surface from
Polynomial Function

Velocity Trend Line
(VTL) per point

Slip Surface from
intersection of VTL

Cross Section Line 2nd



Approx. Surface from
Kinematic model

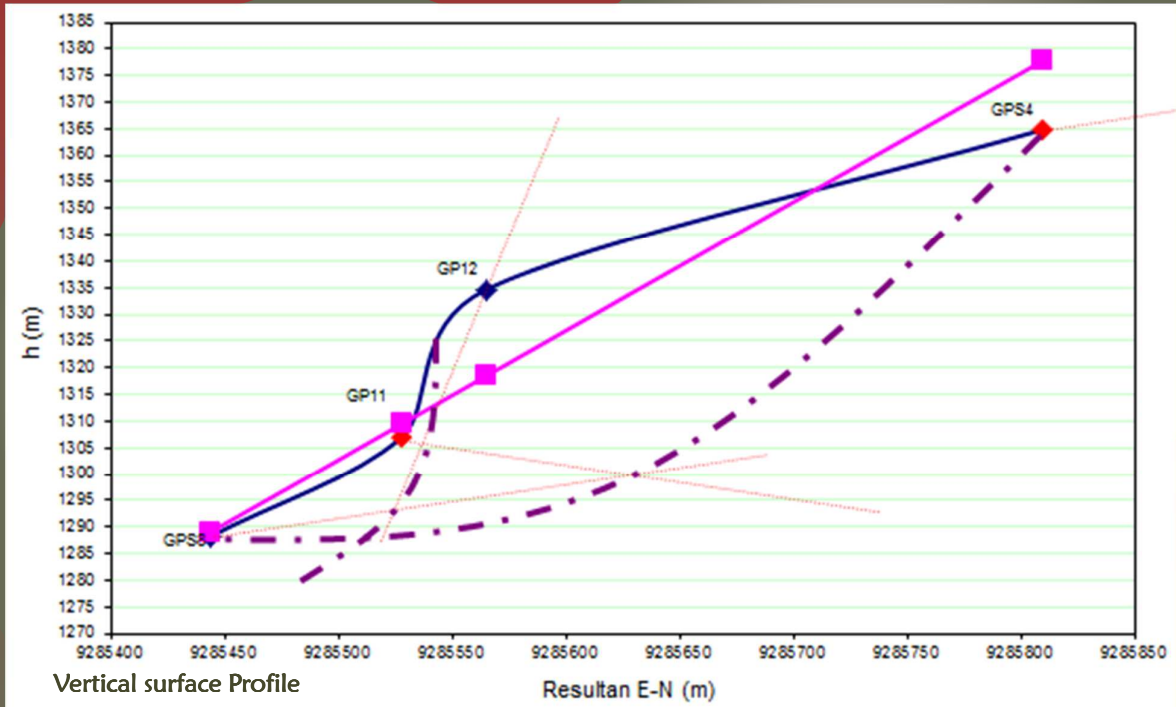
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Approx. Surface from
Polynomial Function

Velocity Trend Line
(VTL) per point

Slip Surface from
intersection of VTL

Cross Section Line 3rd

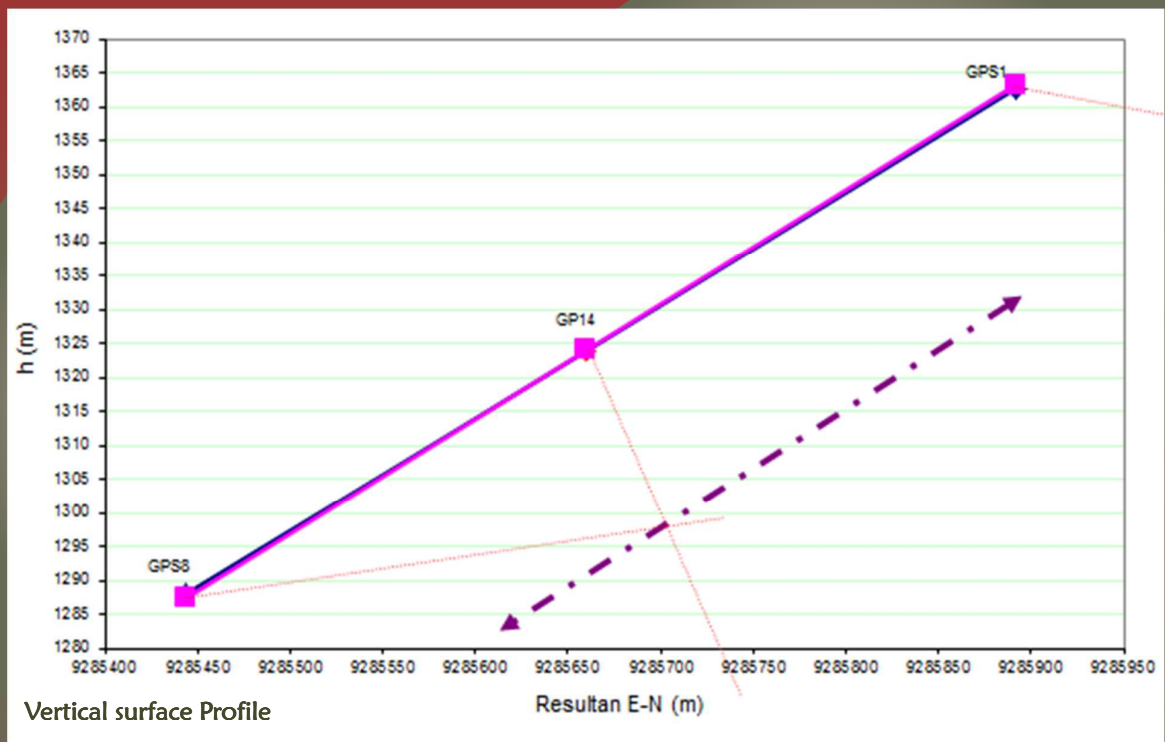


Approx. Surface from
Kinematic model
Approx. Surface from
Polynomial Function

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Velocity Trend Line
(VTL) per point
Slip Surface from
intersection of VTL

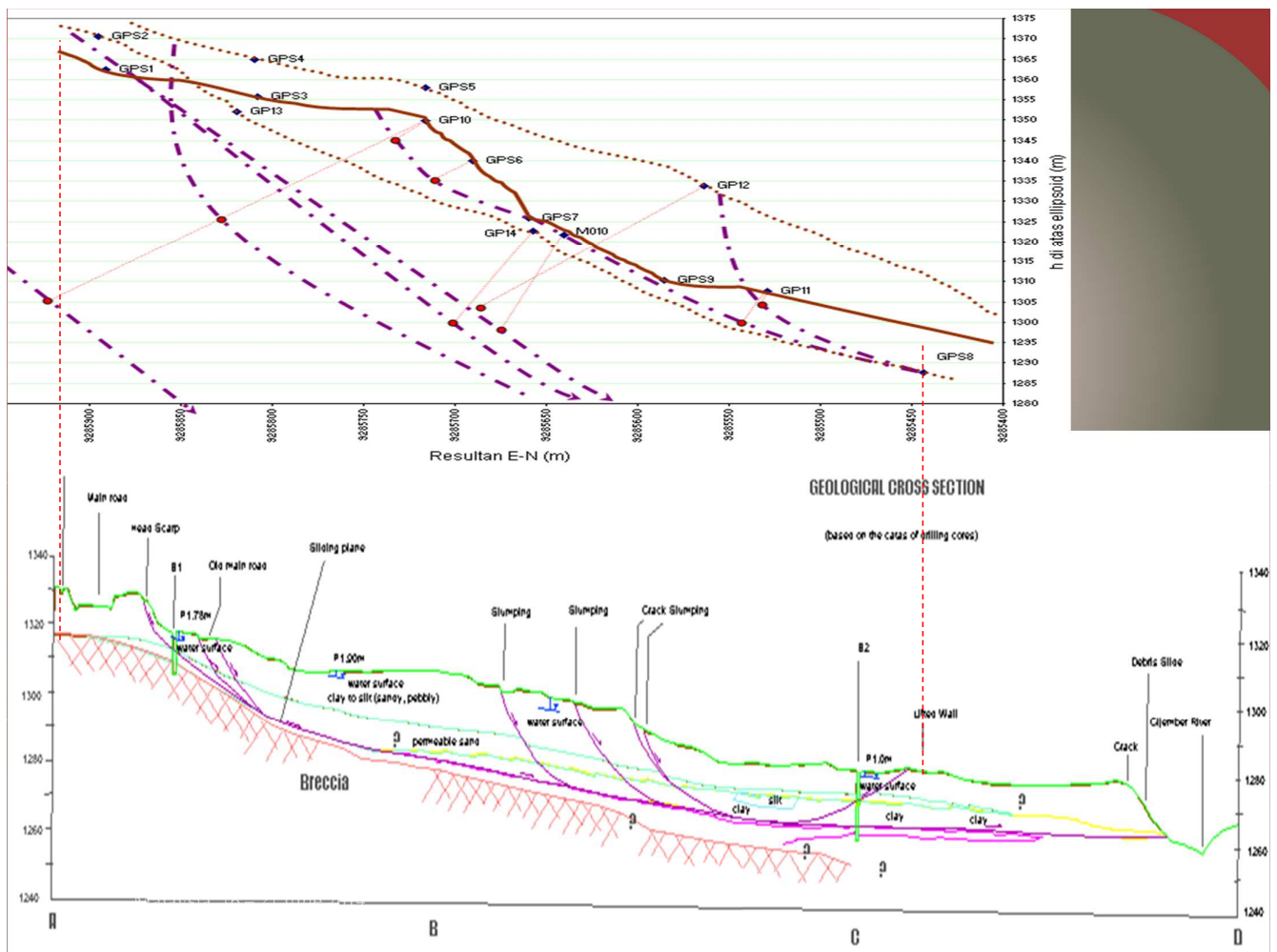
Cross Section Line 4th



Approx. Surface from
Kinematic model
Approx. Surface from
Polynomial Function

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Velocity Trend Line
(VTL) per point
Slip Surface from
intersection of VTL



Conclusion

& Characteristic

- ∞ Displacement Velocity is very slow $5 \times 10^{-5} - 5 \times 10^{-7}$ mm/second
- ∞ Environment effect (rainfall → water infiltration → stress → strain : subsidence/bulging) to material displacement can defined magnitude and direction
- ∞ New minor scarp give information of instability area of landslide zone

& Landslide Type

- ∞ Multiple compound (rotational and translational) debris slide

Landslide Hazard Mitigation

Technical Engineering can applied with information :

- ⌘ **Priority location to minimize water infiltration**
- ⌘ **Location of vulnerable area**
- ⌘ **Direction and magnitude of velocity of material displacement**
- ⌘ **External factor which influence to landslide zone can be defined well, like as river, spring, busy road, farm land**