



# **System for Automatic Crane Measurement**

## **TS9D Machine Guidance and Integrated Measurement Systems**

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## **System for Automatic Crane Measurement**



- **system description**
- **prototype development**
- **system calibration**
- **test measurements**
- **conclusion**

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## **System Description**

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### **Measurement system structure**

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- **robotic measurement station Leica TCA 1101,**
- **standard prisms,**
- **360° prism,**
- **portable operative personal computer,**
- **measured amplifier HBM Spider8,**
- **inductive transducers HBM WA100,**
- **DC/AC power inverter (DC 12V to AC 230V, 50 Hz),  
battery DC 12V**
- **power, terminal and connecting cables.**

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## Measurement system structure

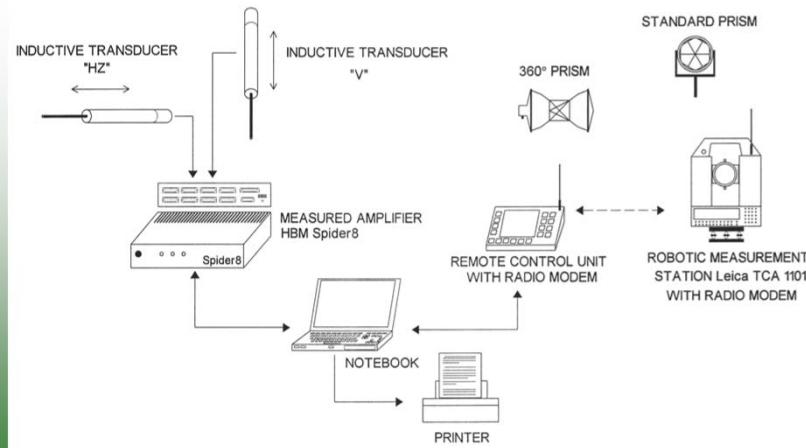


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## Measurement system structure



- **dural U shape bearing structure**

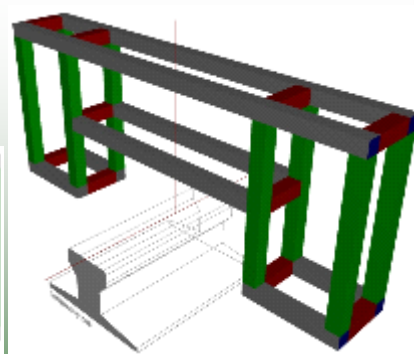
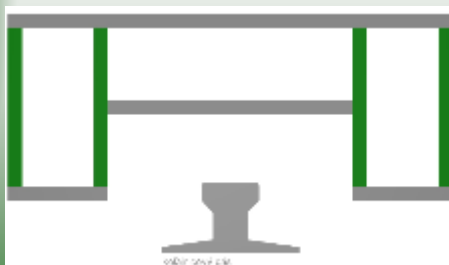


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## Measurement system structure



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## Measurement system structure

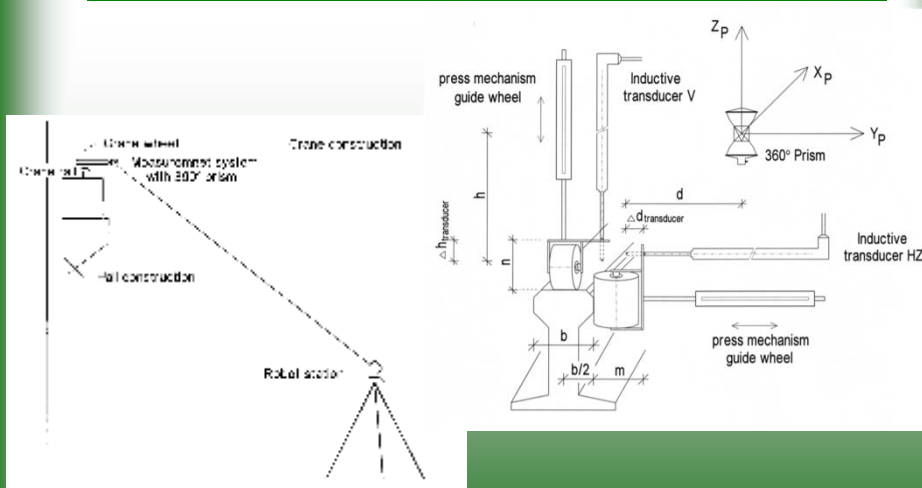


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## Measurement system structure



$$\begin{pmatrix} x \\ y \\ H \end{pmatrix} = \begin{pmatrix} x_p \\ y_p \\ H_p \end{pmatrix} + s \begin{pmatrix} \cos(\beta) \cos(\alpha) \\ \cos(\beta) \sin(\alpha) \\ \sin(\beta) \end{pmatrix} + \cos(\beta_{NK}) \begin{pmatrix} \left( d - \Delta d + m + \frac{b}{2} \right) \cos(\alpha_{NK}) \\ \left( d - \Delta d + m + \frac{b}{2} \right) \sin(\alpha_{NK}) \\ h - \Delta h + n \end{pmatrix}$$

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## Prototype development



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## Prototype development



- dural structure with shifting mechanism
- guide wheel with pressure mechanism
- vertical and horizontal inductive transducers



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## Prototype development



- measuring range 0 – 100 mm
- accuracy 0,01 mm
- linearity < 0,2 %
- measurement rate 0 – 9600 Hz (static and dynamic mode)

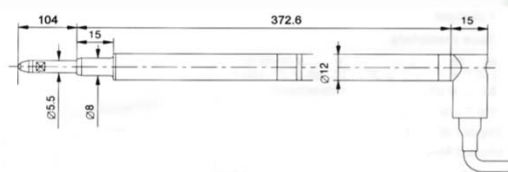


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## Prototype development



- modification of the guide wheels
- magnification of the wheel pressure

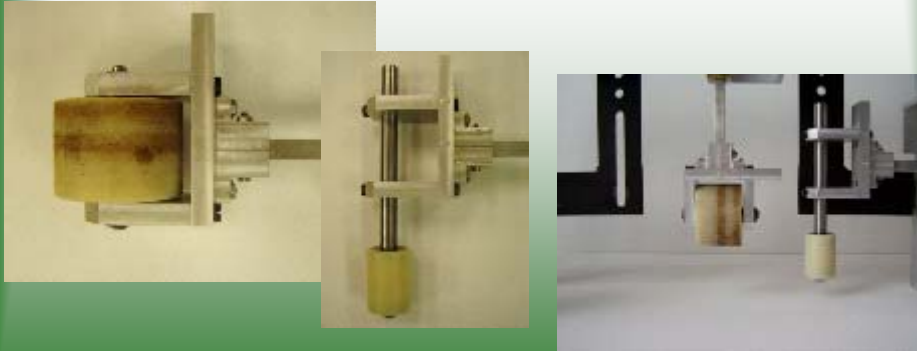


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## Prototype development



- 4 analog and 8 digital inputs
- output for PC – LPT or RS232
- software Conmes Spider

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## ***Prototype development***



- **time synchronization of data acquisition**
- **real-time data processing**
- **track position determination by RTS**



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## ***System calibration***



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## System calibration

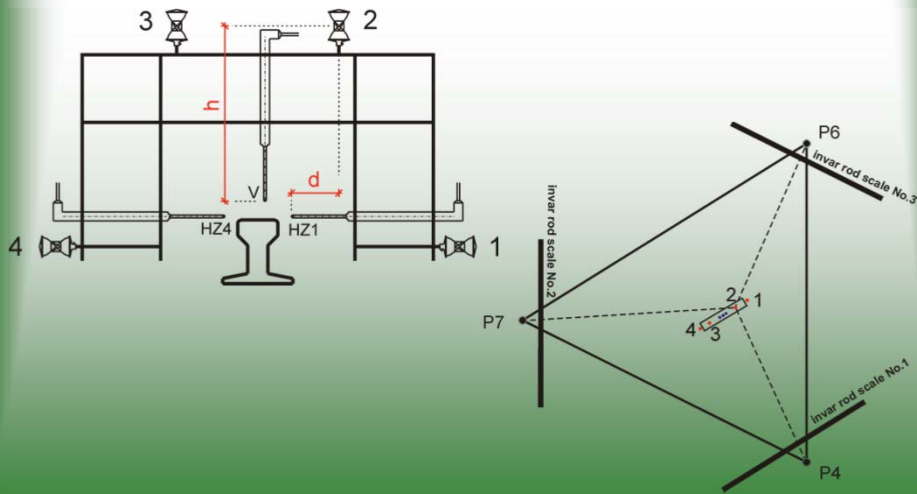


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## System calibration

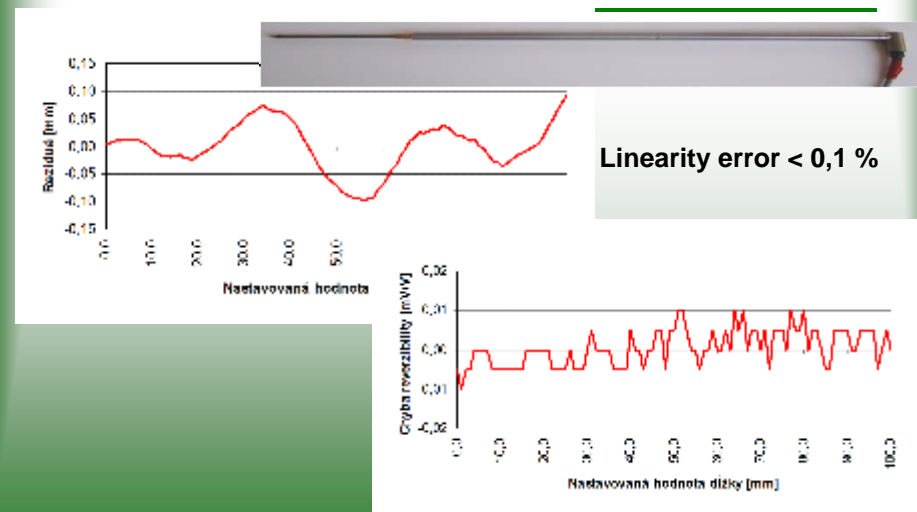


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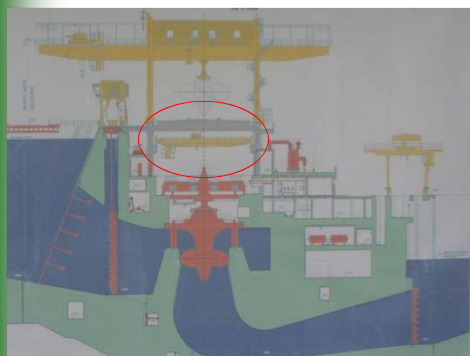


## Test measurements

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### Test measurements



#### ■ HPP Gabčíkovo 8 x 80 MW



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## Test measurements

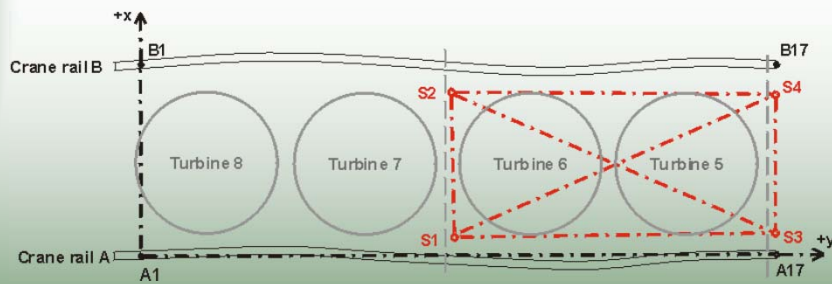


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## Test measurements



- crane geometry 241,0 m x 17,7 m
- 32 tons
- 106,4 m measured length



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## Test measurements

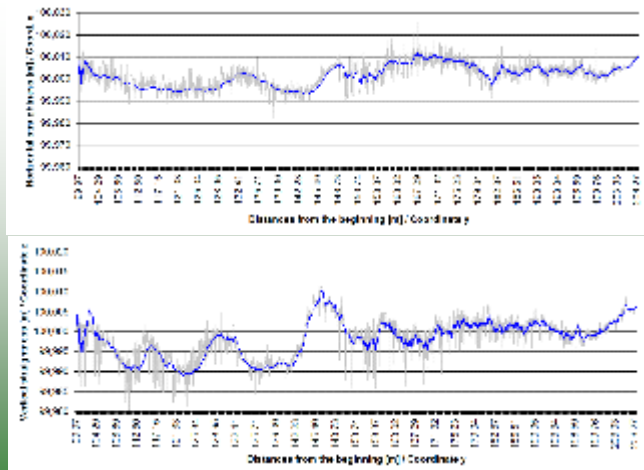


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## Test measurements

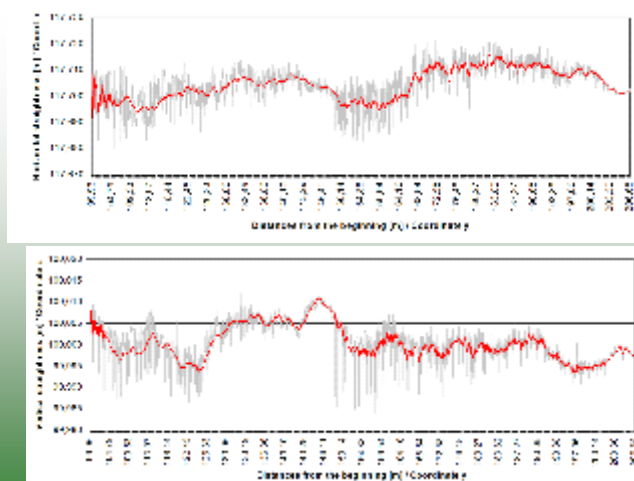


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## Test measurements

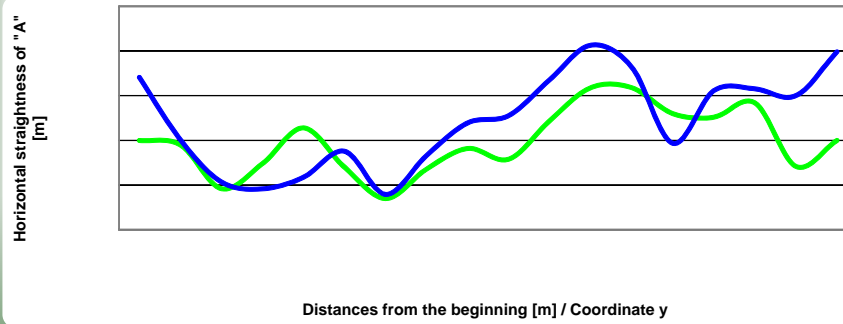


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## Test measurements

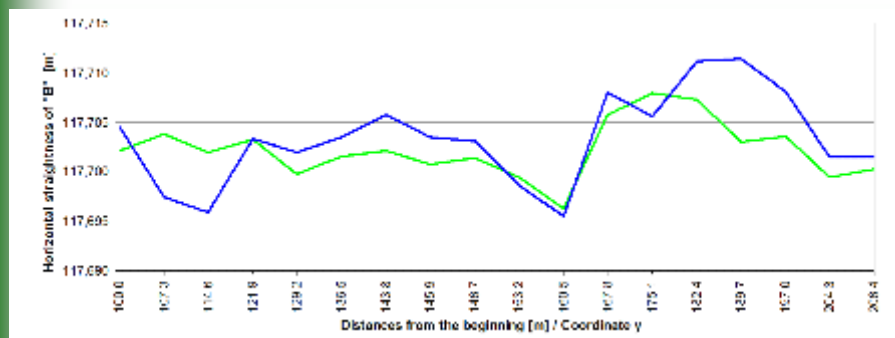


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## Test measurements

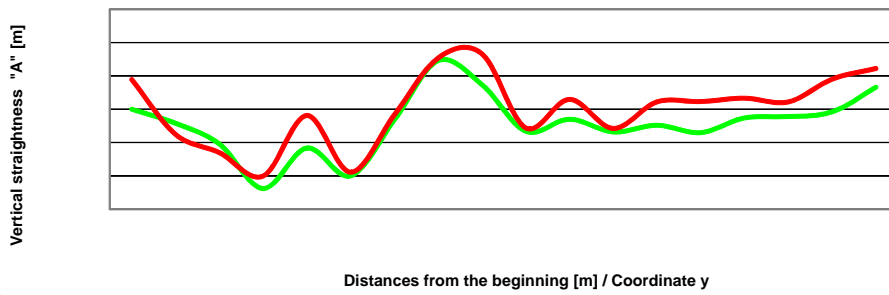


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## Test measurements

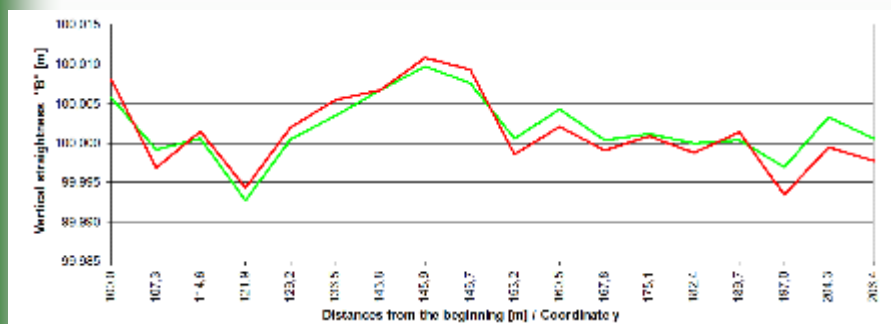


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## **Conclusion**



- **velocity of crane movement up to 5 m/s**
- **density of measured points 38 mm**
- **absolute accuracy achieved 2-3 mm**
- **internal accuracy achieved up to 0.1 mm**
- **maximal safety of measuring personal**
- **changes in standards and methodology**
- **future development**

**Thank you for your attention!**

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